The Effects of Nanosensors Movements on Nanocommunications

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Motivations

- There is no problem if humans move while speaking (sound waves)
- In molecular communication, molecules move, and this poses no problem as well it seems
- In elmagn communication, antennas are not alive, they do not move (GWNoC for ex.)
 - but if they are put inside other thing (such as human body or nanorobot), they *could* move even during the same communication
- But... is there any problem if they move?! Let's dig into this...

The problem: TS-OOK modulation peculiarities

- Nanonodes have size and power constraints => very challenging to generate a carrier => TS-OOK pulse-based modulation proposed
- In Time Spread On-Off Keying modulation, bit 1 is a pulse, bit 0 is silence (*Jornet & Akyildiz, TrComm 2014*)
- In order for this to work, nodes need to be tightly synchronised, is that fine if nodes move?!
 On sender:



- Direct effects of receiver movement taken into account in the following:
 - change in timing (**when** pulses arrive at receiver, pulse time-shift)
 - change in frequency of the signal (Doppler effect)
 - change in distance => change in bit error rate and information rate

Pulse time-shift



Pulse time-shift – numerical example



• $T_p = 10^{-12} \text{ s}, T_s = 10^{-9} \text{ s}$ (spreading factor β =1000)

 $t_{\text{shift}} = 0.8 \times 10^{-17} (s)$ $t_{\text{percentage}} = 8 \times 10^{-4} \%$

Conclusions:

- too small for 1 bit transmission, hence no problem
- reaches 100% (creates ISI) at the 125000th bit, i.e. at the 16th kB or after 0.125 ms or after 0.3 meters => countermeasures need to be taken

Doppler effect

"Change in frequency because of movement"

$$\Delta f = \frac{v}{c} f_0$$

where f_o is the frequency, v receiver speed and c speed of the light

- Numerical example:
 - v = 2.4 m/s
 - first derivative of Gaussian TS-OOK pulse, signal is centered at around $f_o = 1.6$ THz
 - then $\Delta f \approx 10$ kHz
- So change in frequency is negligible



Bit error rate increase

Receiver moves away => distance snd/rcv increases => BER should increase

$$BER = P(e|X = 0)P(X = 0) + P(e|X = 1)P(X = 1)$$

Probability of error when bit x is transmitted:

$$P(e|x=0) = P(y=1|x=0) = 1 - \int_{A}^{B} P(Y|x=0) \, dy$$
(26)

$$P(e|x=1) = P(y=0|x=1) = \int_{A}^{B} P(Y|x=1) \, dy \quad (27)$$

$$P(Y|X = x_i) = \frac{1}{\sqrt{2\pi N_i}} e^{-\frac{(y-a_i)^2}{2N_i}}$$
 (Jornet & Akyildiz, TrComm 2014)

where:

- N_i total noise power for transmitted signal x_i
- a, amplitude of the received symbol

Bit error rate increase – simulation results



- BER changes significantly
- Some applications have BER constraints, e.g. video streaming needs BER < 10⁻⁴ (v should be smaller than 1 cm/s in the example)
- If BER is too high, error correction codes, ... are required

Information rate reduction

Receiver moves away => distance snd/rcv increases => IR should decrease

$$IR = C \times \frac{B}{\beta} \quad (bit/second)$$
Numerical results:
• B = 10¹³ (in THz band)
• $\beta = 1000$
• initial distance = 1 mm
• 10 sec movement with various speeds
Conclusion:
• if moving with 10 cm/s for 10 seconds

- If moving with 10 cm/s for 10 seconds, IR decreases from 10 to 4 Gb/s in this example
- IR changes significantly

Conclusions and perspectives

- Node movement is worth taking into account
- Without synchronisation, problems (such as ISI) can arise
 => there is a need for synchronisation algorithms used by nanonodes
- BER and IR could change significantly when moving
 => the type of motion should be taken into account in communication protocols
- Doppler effect is negligible
- All code to regenerate the results of the paper are available on my Web page (http://eugen.dedu.free.fr)